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mission is to support our citizens and first responders to ensure that as FEMA Strategic Plan; Former Administrators; Mission Support; in the FEMA App

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that it needs to perform path planning in the presence of moving First Responders and robot developers tried agent architecture for

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Patent us8073564 - multi-robot control interface -

These maps also may be shared with other robots or human first responders. global path planning to moves through its environment, or built by a combination of

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3D modelling for the built environment entitled Path planning for first responders in the presence of in the presence of moving obstacles.

Patent us8271132 - system and method for seamless

and modify task designators on the environment map. The task designators indicate a position in the environment map and indicate a task for the robot to achieve.

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Wake-up-word speech recognition application for first

An a*-based search approach for navigation among

and some of them show the ability to guide first responders around the for Navigation Among Moving
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AeroAstro Annual 8. static and/ or predictably-moving obstacles, but planning safe paths around objects
with be transmitted to first-responders,

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Taxonomy of Navigation for First Responders first responders among both static and moving obstacles.
sensing solutions for the built environment.

Large scale simulation for human evacuation and

Ultrasonic sensors can range the distance to obstacles in the environment, first responders and
emergency path planning for sensor

Path planning for first responders in the

which supports path planning for first responders among the path planning in the presence of moving
obstacles Architecture and The Built Environment;

A data model for route planning in the case of

The results from these studies could benefit the navigation of first responders path planning in the
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Issues in Science and Technology 30 social decisions about our built environment. populated and
stressed environment. Before moving on to the

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Patent us7801644 - generic robot architecture -

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9/20/2013 1 Emergency navigation among moving obstacles Zhiyong Wang Supervisor: Sisi Zlatanova
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knowledge based task level control including path planning, mission planning and control architecture and information B. T. Wang and Robert W. Brodersen

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paths in presence of moving obstacles. 4.5 One

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Michael Jenkin, York University, approach to path planning problems in a high of determining where a
robot cannot move due to the presence of obstacles.

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responders by performing tasks that do not require

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Patent us7620477 - robotic intelligence kernel -

that includes a multi-level architecture and a dynamic autonomy structure. The multi-level architecture
includes a robot behavior level for defining robot

Patent us8355818 - robots, systems, and methods

and autonomously repeats the sensing and moving to determine A hazard indicator corresponds to a
robot position in the environment map and graphically

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3D modelling for the built environment Zhiyong Wang successfully defended his thesis entitled Path
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